Intelligent Traffic Monitoring and Control A Hybrid IoT and Q-Learning Approach CS974 (Internet of Things)

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1 Problem Statement

2 IoT Architecture for Urban Intelligence

- Key IoT Components
- IoT-Enabled Traffic Control Strategies
- Challenges and Solutions

3 Q-Learning for Signal Optimization

Deep Q-Network Design

4 Performance Results

Synergy of IoT and Q-LearningConclusion

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Problem Statement

- Urban traffic congestion caused by static signal systems [Li et al. (2020)]
 - Consequences:
 - Time loss, fuel wastage, environmental pollution
 - Delayed emergency response
 - Need for real-time adaptive solutions



Problem Statement

2 IoT Architecture for Urban Intelligence

- Key IoT Components
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- Challenges and Solutions

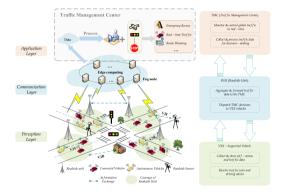
Q-Learning for Signal Optimization

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IoT Architecture for Urban Intelligence

- Three-layer architecture:
 - Application Layer: Traffic Management Center (TMC) with cloud/fog computing
 - Communication Layer: RSUs, 5G/V2V/V2I networks [Lu et al. (2014)]
 - Perception Layer: Sensors, cameras, V2X-supported vehicles
- Key components:
 - Vehicle-to-Everything (V2X) communication
 - Real-time data collection and processing



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Key IoT Components

V2X-Supported Vehicles:

- Equipped with GPS, sensors, and communication modules
- Share real-time position and speed data [Chavhan et al. (2019)]

Roadside Units (RSUs):

- Aggregate traffic data within coverage zones
- Act as fog computing nodes

Traffic Management Center (TMC):

- Centralized cloud system for decision-making
- Implements optimal control strategies

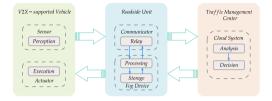
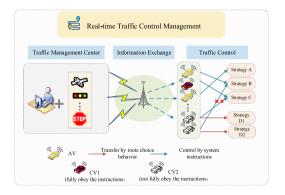


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IoT-Enabled Traffic Control Strategies

- Strategy A: Idle capacity-based rerouting
- Strategy B: Dynamic edge connectivity-based rerouting
- Strategy C: Edge betweenness-based rerouting
 - Emergency Priority: Dynamic lane clearance for emergency vehicles
 - **Performance Metrics**: Congestion levels (TTI), recovery time



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Challenges and Solutions

Data Reliability:

- Challenge: Sensor noise/outliers
- Solution: Redundant data sources and validation

Latency:

- Challenge: Real-time decision requirements
- Solution: Edge computing with RSUs

Scalability:

- Challenge: City-wide deployment
- Solution: Modular zone-based architecture



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Overview

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Q-Learning for Signal Optimization

- Objective: Minimize cumulative waiting time
- State Space: Vehicle counts per lane, signal phase
- Action Space: Signal duration adjustments
- Reward Function: Negative of waiting time [Olayode et al. (2020)]

Theorem 3.1: Update Rule

$$Q(s,a) \leftarrow Q(s,a) + \alpha [r + \gamma \max_{a'} Q(s',a') - Q(s,a)]$$

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Deep Q-Network Design

Input Layer: Traffic state (16 features)

Convolutional Layers:

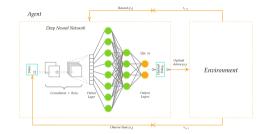
- Layer 1: 16 filters (4x4), stride 2, ReLU
- Layer 2: 32 filters (2x2), stride 1, ReLU

Fully Connected Layers:

- FC1: 128 units, ReLU
- FC2: 64 units, ReLU

Output Layer: Q-values for each action

Experience Replay: Stabilizes training [Zhao et al. (2024)]



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Performance Results

Benchmark Comparison:

- Static system: 330k seconds waiting time
- Our model: 190k seconds (avg), 126k seconds (best)
- Improvement: 61.8% reduction in waiting time

Key Advantages:

- Adapts to real-time traffic conditions [Zhang et al. (2011)]
- Scalable to complex intersections [Gao and Wang (2021)]

Synergy of IoT and Q-Learning

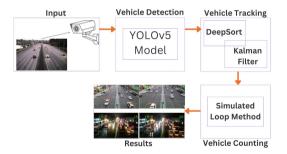
IoT Provides:

Real-time traffic data collection
 City-wide coordination capability

Q-Learning Provides:

 Local intersection optimization
 Adaptive learning without explicit programming

Combined Benefit: Macro-micro control integration

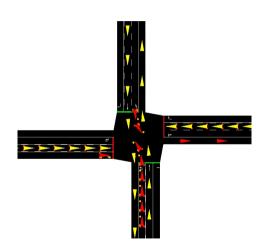


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Conclusion

- Demonstrated 61.8% improvement over static systems
- IoT enables real-time monitoring and control
- Q-learning provides adaptive optimization
 Future work:
 - Multi-agent coordination for city-scale deployment [Liang et al. (2022)]



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